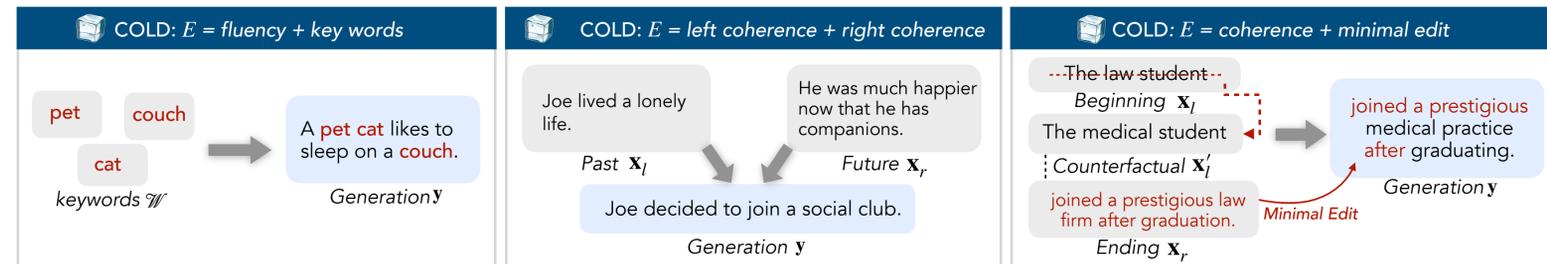


COLD Decoding: Energy-based Constrained Text Generation with Langevin Dynamics

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Text generation requires producing text that is not only **fluent**, but also satisfies different **constraints** that control the semantics or style of the generated text.



The dominant approach: fine-tune a pretrained LM with task-specific data

- prohibitively expensive
- can hardly scale to the infinite possible combinations of constraints

This work: constrained generation as sampling from an **energy-based model (EBM)**:

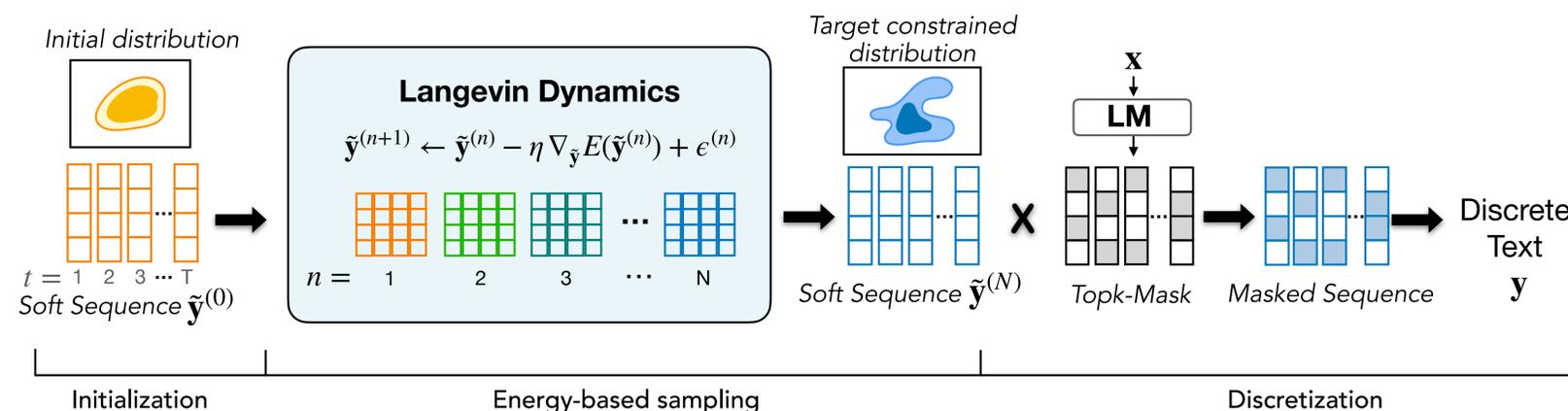
- specify an energy function by plugging in any desired constraint functions
- then sample from the induced energy-based distribution
- No training/finetuning — control on the fly!

$$p(\mathbf{y}) = \exp \left\{ \sum_i \lambda_i f_i(\mathbf{y}) \right\} / Z,$$

Key challenge of sampling from the text EBM:

- the normalizing factor Z is intractable
- the common discrete MCMC methods (e.g., Gibbs sampling) is too inefficient!

Solution: Use **gradient-based MCMC, Langevin dynamics**, for efficient sampling!



- continuous relaxation of discrete text: each token y_t is modeled with its logit vector $\tilde{\mathbf{y}}_t$
- Langevin dynamics: $\tilde{\mathbf{y}}^{(n+1)} \leftarrow \tilde{\mathbf{y}}^{(n)} - \eta \nabla_{\tilde{\mathbf{y}}} E(\tilde{\mathbf{y}}^{(n)}) + \epsilon^{(n)}$
- Discretize the sampled continuous text vector with *top-k filtering* (see paper for more details)

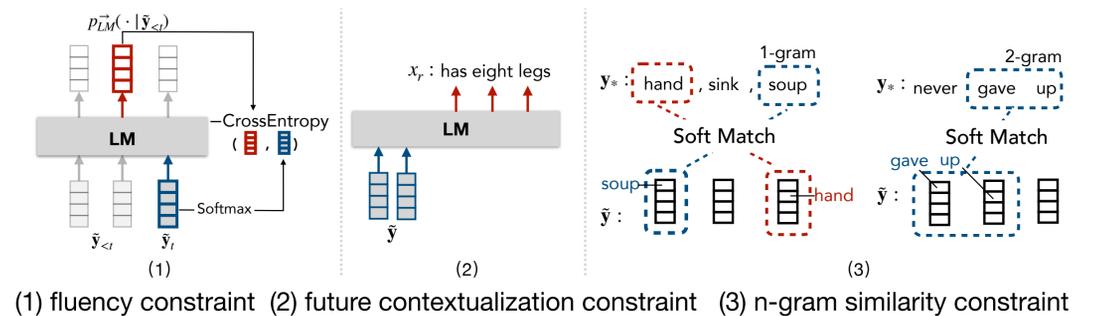
Algorithm of COLD

Algorithm 1 Constrained Decoding w/ Langevin Dynamics.

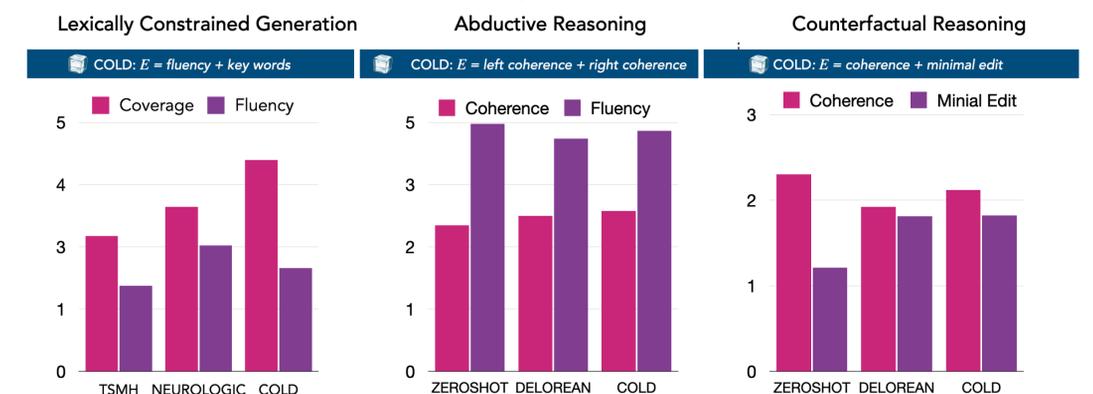
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input Constraints  $\{f_i\}$ , length  $T$ , iterations  $N$ .
output Sample sequence  $\mathbf{y}$ .
 $\tilde{\mathbf{y}}_t^{(0)} \leftarrow \text{init}()$  for all position  $t$  // init soft-tokens
for  $n \in \{1, \dots, N\}$  do
     $E^{(n)} \leftarrow E(\tilde{\mathbf{y}}^{(n)}; \{f_i\})$  // compute energy (§3.2)
     $\tilde{\mathbf{y}}_t^{(n+1)} \leftarrow \tilde{\mathbf{y}}_t^{(n)} - \eta \nabla_{\tilde{\mathbf{y}}_t} E^{(n)} + \epsilon_t^{(n)}$  for all  $t$  // update soft tokens (Eq.2)
end for
 $y_t = \arg \max_v \text{topk-filter}(\tilde{\mathbf{y}}_t^{(N)}(v))$  for all  $t$  // discretize (Eq.6)
return:  $\mathbf{y} = (y_1, \dots, y_T)$ 
    
```

Illustrations of example differentiable constraints



Experiment Results



Check out COLD decoding paper!!

